THE TAU METHOD

Problem #35, page 329 of A First Course in Numerical Analysis by Ralston and Rabinowitz.

P670 Numerical Analysis, Prof. Fair

-*35 The τ method. Consider the differential equation

(1)
$$L(y) = p_n(x) \frac{d^n y}{dx^n} + p_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + p_0(x)y + P(x) = 0$$

$$(2) \qquad y(0) = y_0 \qquad y^{(i)}(0) = y_i \qquad i = 1, \dots, n-1$$

where $p_j(x)$ is a polynomial of degree d_j and P(x) is a polynomial of degree d.

(a) Assume a solution.

(3)
$$y(x) = \sum_{j=0}^{m} a_{j}x^{j} \qquad m \ge n$$
 and let (4)
$$D = \max (d, d_{0} + m, d_{1} + m - 1, ..., d_{n} + m - n)$$

Show that substituting this solution into the differential equation leads in general to a system of D + 1 + n equations in m + 1 unknowns if the initial conditions are to be satisfied.

(b) Show that, in general, the differential equation

(5)
$$L(y) = \sum_{i=1}^{D-m+n} \tau_i T_{m-n+i}^*(x)$$

does have a solution of the form of part (a), where the τ_i 's are real numbers and T_{m-n+i}^* is the shifted Chebyshev polynomial of degree m-n+i (see Prob. 23). Thus deduce that if the τ_i 's are small, the solution of this differential equation is a good approximation to the solution of $\mathcal{L}(y) = 0$.

(c) Use this method with m=4 to approximate e^x . Draw a graph of the error on [0, 1] and compare this with the error in $R_{4,0}(x)$ on [0, 1]. [This method is of particular value when f(x) does not have a convergent polynomial or continued-fraction expansion.] [Ref.: Lanczos (1956), pp. 464-469.]

Differentiation of (3) yields:

(6)
$$y'(x) = \sum_{j=0}^{m} j(j-1) \cdots (j-k+1) a_j x^{j-k}$$

Substitution of the boundary conditions (2) into equations (3) and (6) yields:

$$a_0 = y_0$$
 $a_1 = y_1$ $a_2 = y_2/2$ $a_{n-1} = y_{n-1}/(n-1)!$

Thus n constants, a_0 to a_{n-1} , are determined by the initial conditions, and (m-n+1) unknowns, a_n to a_m^{n-1} , remain to be determined.

Note that the maximum degree of x in y is m, in $y^{(1)}$ is m-1, ..., in $y^{(n)}$ is m-n. So using (4), D is the maximum degree of x in equation (1). Since L(y) must equal zero, the coefficient of each power of x, from \dot{x} to x^D , must equal zero. This gives D+1 equations in m-n+1 unknowns, a^* to a^* . Since the minimum value of D is m, there will always be more equations than unknowns and in general this overdetermined system will not have a solution.

Overall, there were (D+1)+n equations with (m-n+1)+n=m+1 unknowns, a_0 to a_m .

When we substitute a finite power series for y into equation (1), it is generally impossible to solve the resulting overdetermined system. Consider solving (5) instead, where zero has been replaced by a sum of shifted Chebyshev polynomials of the proper degree. Since the shifted Chebyshev polynomials have the min-max property over the range x from Therefore if the τ_i 's are small, then $L(y) \approx 0$ and the solution of (5) is a good approximation to the solution of (1). 0 to 1, and have a peak value of 1, the peak value of the right hand side

From (5), we have a sum of shifted Chebyshev polynomials, T_D^* , T_{D-1}^* ,, T_{m-n+1}^* , with (D-m+n) unknowns, $T_1 \cdots T_{D-m+n}$.

Note that the highest degree of x is D. After solving the initial conditions, substituting (3) into (5) now yields (D+1) equations in (m-n+1)+(D-m+n)=D+1unknowns, and thus in general a solution will exist.

Example e^{X} satisfies the differential equation L(y)=y-y'=0.

let
$$y= a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4$$
.

then
$$y' = a_1 + 2a_2x + 3a_3x^2 + 4a_4x^3$$
.

The boundary condition y(0)=1 yields $a_0=1$.

Note that m=4, n=1, D=max(0,0+m,0+m-1)=m=4, D-m+n=1, and the error term is ΥT_A .

Equation (5) becomes in this case:

$$L(y) = y - y' = (1 - a_1) + (a_1 - 2a_2)x + (a_2 - 3a_3)x^2 + (a_3 - 4a_4)x^3 + a_4x^4 = \dots$$

$$= 7[1 - 32x + 160x^2 - 256x^3 + 128x^4].$$

where $T_4^* = 1 - 32x + 160x^2 - 256x^3 + 128x^4$. (The shifted polynomial T_n^* can be derived from T_n by a change of variables, $T_n^*(x) = T_n(2x-1)$.)

Equate powers of x on the left and right hand sides:

$$\begin{vmatrix}
1-a_1 & \tau \\
a_1-2a_2 & -32\tau \\
a_2-3a_3 & 160\tau \\
a_3-4a_4 & -256\tau \\
a_4 & 128\tau
\end{vmatrix}$$

This system of five equations in five unknowns can be solved by hand using Gaussian elimination and back substitution with exact arithmetic. The solution is:

$$a_1$$
= 1824/1825. $= 1/1825.= .548 E-3$
 a_2 = 928/1825.
 a_3 = 256/1825.
 a_4 = 128/1825.

Thus,
$$y(x) = 1 + \frac{1824}{1825}x + \frac{928}{1825}x^2 + \frac{256}{1825}x^3 + \frac{128}{1825}x^4$$
.

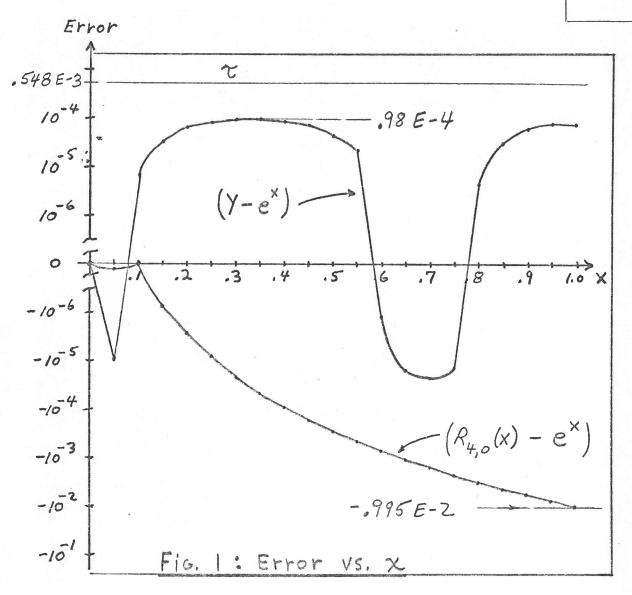
Compare this expression with the fourth-order Taylor series approximation to e^X : $R_{4,0}(x) = 1 + x + \frac{1}{2} x^2 + \frac{1}{6} x^3 + \frac{1}{24} x^4$.

Table 1 shows the results of a Fortran program run to compare e^X with the approximation, $\tilde{R}_{4,0}(x)$, (Taylor series), and with the Tau approximation, Y(x). The errors of each are plotted in figure 1.

The Taylor series approximation has less error than the Tau method for x between 0 and .35 . This is to be expected, since the Taylor series approximation satisfies five boundary conditions at x=0 , and is most accurate near that point. The Tau approximation has an error bounded by .98 E-4, for x between .4 and 1 , but the error in R_{4} 0 increases by two orders of magnitude beyond this over the same interval.

(The anomalous point ER=0.0 at x=.1 should be recomputed using double precision)

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Taylor Series Approximation to
$$e^{x}$$
:
$$R_{4,0}(x) = 1 + x + \frac{x^{2}}{2} + \frac{x^{3}}{6} + \frac{x^{4}}{24}.$$

TAU Method to Approximate ex:

$$Y(x) = 1 + \frac{1824}{1825} \times + \frac{928}{1825} \times^2 + \frac{256}{1825} \times^3 + \frac{128}{1825} \times^4$$