

7. Q4

\$ python ./x86.py -p flag.s -R ax,bx -a bx=2 -M flag,count -c -i 6

				flag count		ax	bx	Thread 0	Thread 1
flag	count	ax	bx	Thread 0	Thread 1				
						1	1	1001 test \$0, %ax	
						1	1	1002 jne .acquire	
0	0	0	2			1	1	1003 mov \$1, flag	
0	0	0	2	1000 mov flag, %ax		1	1	1004 mov count, %ax	
0	0	0	2	1001 test \$0, %ax		1	1	1005 add \$1, %ax	
0	0	0	2	1002 jne .acquire		1	2	1006 mov %ax, count	
1	0	0	2	1003 mov \$1, flag		1	2	----- Interrupt -----	----- Interrupt -----
1	0	0	2	1004 mov count, %ax		1	2		1006 mov %ax, count
1	0	1	2	1005 add \$1, %ax		0	2		1007 mov \$0, flag
1	0	0	2	----- Interrupt -----	----- Interrupt -----	0	2		1008 sub \$1, %bx
1	0	1	2		1000 mov flag, %ax	0	2		1009 test \$0, %bx
1	0	1	2		1001 test \$0, %ax	0	2		1010 jgt .top
1	0	1	2		1002 jne .acquire	0	2		1000 mov flag, %ax
1	0	1	2		1000 mov flag, %ax	0	2	----- Interrupt -----	----- Interrupt -----
1	0	1	2		1001 test \$0, %ax	0	2	1007 mov \$0, flag	
1	0	1	2		1002 jne .acquire	0	2	1008 sub \$1, %bx	
1	0	1	2	----- Interrupt -----	----- Interrupt -----	0	2	1009 test \$0, %bx	
1	1	1	2	1006 mov %ax, count		0	2	1010 jgt .top	
0	1	1	2	1007 mov \$0, flag		0	2	1011 halt	
0	1	1	1	1008 sub \$1, %bx		0	2	----- Halt;Switch -----	----- Halt;Switch -----
0	1	1	1	1009 test \$0, %bx		0	2		1001 test \$0, %ax
0	1	1	1	1010 jgt .top		0	2	----- Interrupt -----	----- Interrupt -----
0	1	0	1	1000 mov flag, %ax		0	2		1002 jne .acquire
0	1	1	2	----- Interrupt -----	----- Interrupt -----	1	2		1003 mov \$1, flag
0	1	0	2		1000 mov flag, %ax	1	2		1004 mov count, %ax
0	1	0	2		1001 test \$0, %ax	1	2		1005 add \$1, %ax
0	1	0	2		1002 jne .acquire	1	3		1006 mov %ax, count
1	1	0	2		1003 mov \$1, flag	0	3		1007 mov \$0, flag
1	1	1	2		1004 mov count, %ax	0	3	----- Interrupt -----	----- Interrupt -----
1	1	2	2		1005 add \$1, %ax	0	3		1008 sub \$1, %bx
1	1	0	1	----- Interrupt -----	----- Interrupt -----	0	3		1009 test \$0, %bx
						0	3		1010 jgt .top
						0	3		1011 halt